Notice of References Cited Application/Control No. 10/810,188 Examiner Lin B. Olsen Applicant(s)/Patent Under Reexamination FUKUCHI ET AL. Page 1 of 1

U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	Α	US-6,255,793 B1	07-2001	Peless et al.	318/580
*	В	US-6,539,284 B2	03-2003	Nourbakhsh et al.	700/245
*	С	US-6,917,855 B2	07-2005	Gonzalez-Banos et al.	700/245
*	D	US-7,054,716 B2	05-2006	McKee et al.	700/245
*	ш	US-7,135,992 B2	11-2006	Karlsson et al.	340/995.1
*	F	US-7,085,624	08-2006	Aldred et al.	700/253
	G	US-			
	Н	US-			
	1	US-			
	J	US-			
	К	US-			
	L	US-			
	М	US-			

FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N					
	0					
	Р					
	Q					
	R					
	S					
	Т					

NON-PATENT DOCUMENTS

	NON-FAIENT DOCUMENTS					
*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)				
	υ	Sabe, Fukuchi, Gutmann, Ohashi, Kawamoto and Yoshigahara, "Obstacle Avoidance and Path Planning for Humanoid Robots using Stereo Vision", Proceedings 2004 IEEE Int. Conf on Robotics & Automation, April 2004, Pgs 592-597.				
	v	Guttmann, Fukuchi, and Sabe, "Environment Identification by Comparing Maps of Landmarks", Proceedings of the 2003 IEEE Int. Cnf on Robotics & Automation, Sept 2003, Pgs 262-267.				
	w	Montemerlo and Thrun, " Simultaneous Localization and Mapping with Unknown Data Association Using FastSLAM", Proceedings of 2003 IEEE Int Conf on Robotics & Automation , Spt 2003, Pgs 1985-1991.				
	×	Mata, Armingol, De la Escalera and Salichs, "A Visual Landmark Recognition System for Topoligical Navigation of Mobile Robots", Proceedings of 2001 IEEE Int. Conf. on Robotics & Automation, May 2001, Pgs 1124-1129				

*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)

Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.